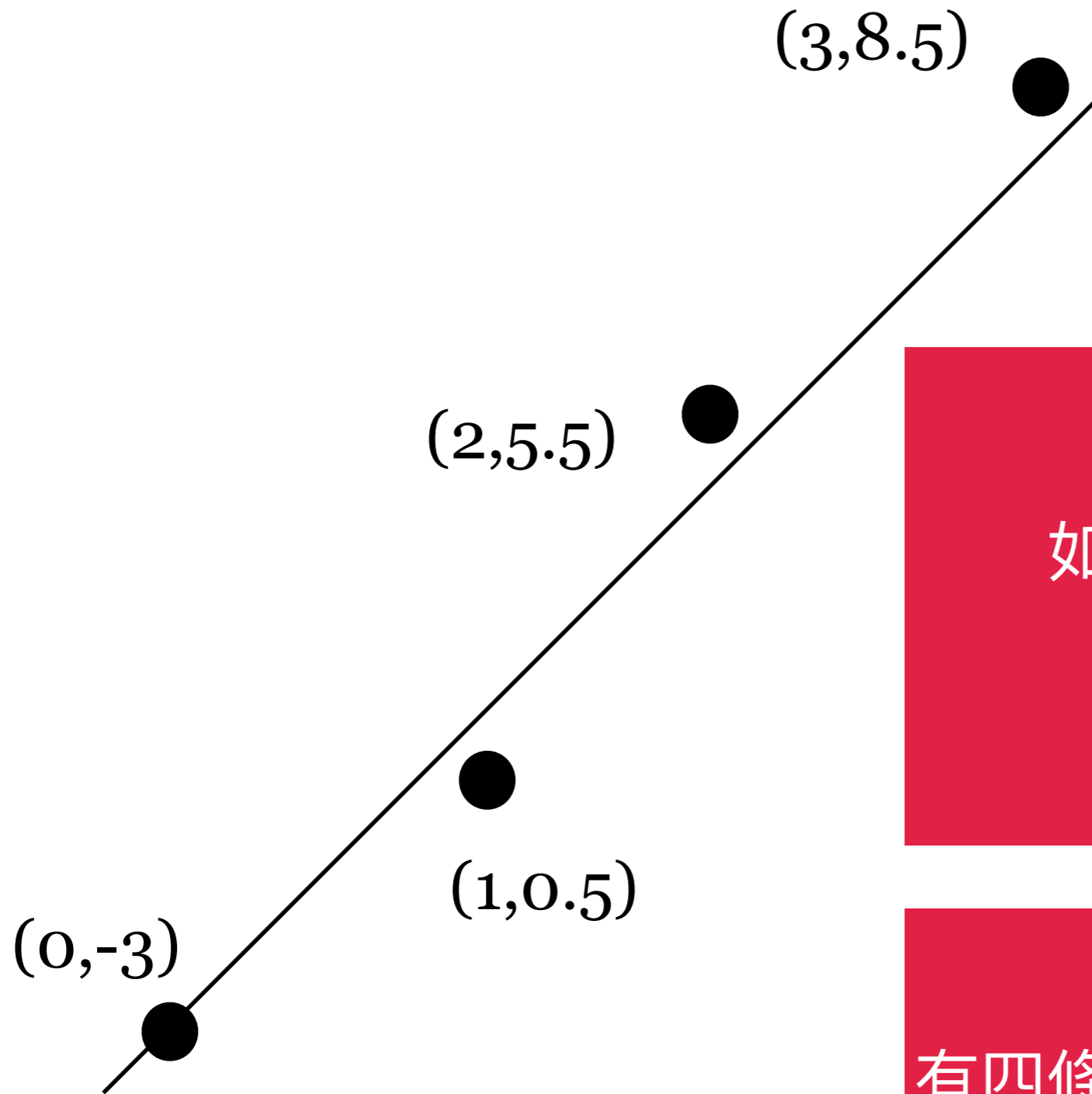


反矩陣的資料分析應用

給不共線的多個點求一直線



四點不共線
如何求出最好的一條線，
描述這四點呢？

線性系統是長方形的
有四條方程式，但是只有兩個未知
數

步驟一：匯入
套裝

```
import numpy as np  
from numpy.linalg import inv
```

步驟二：將資料以
矩陣A向量b表示

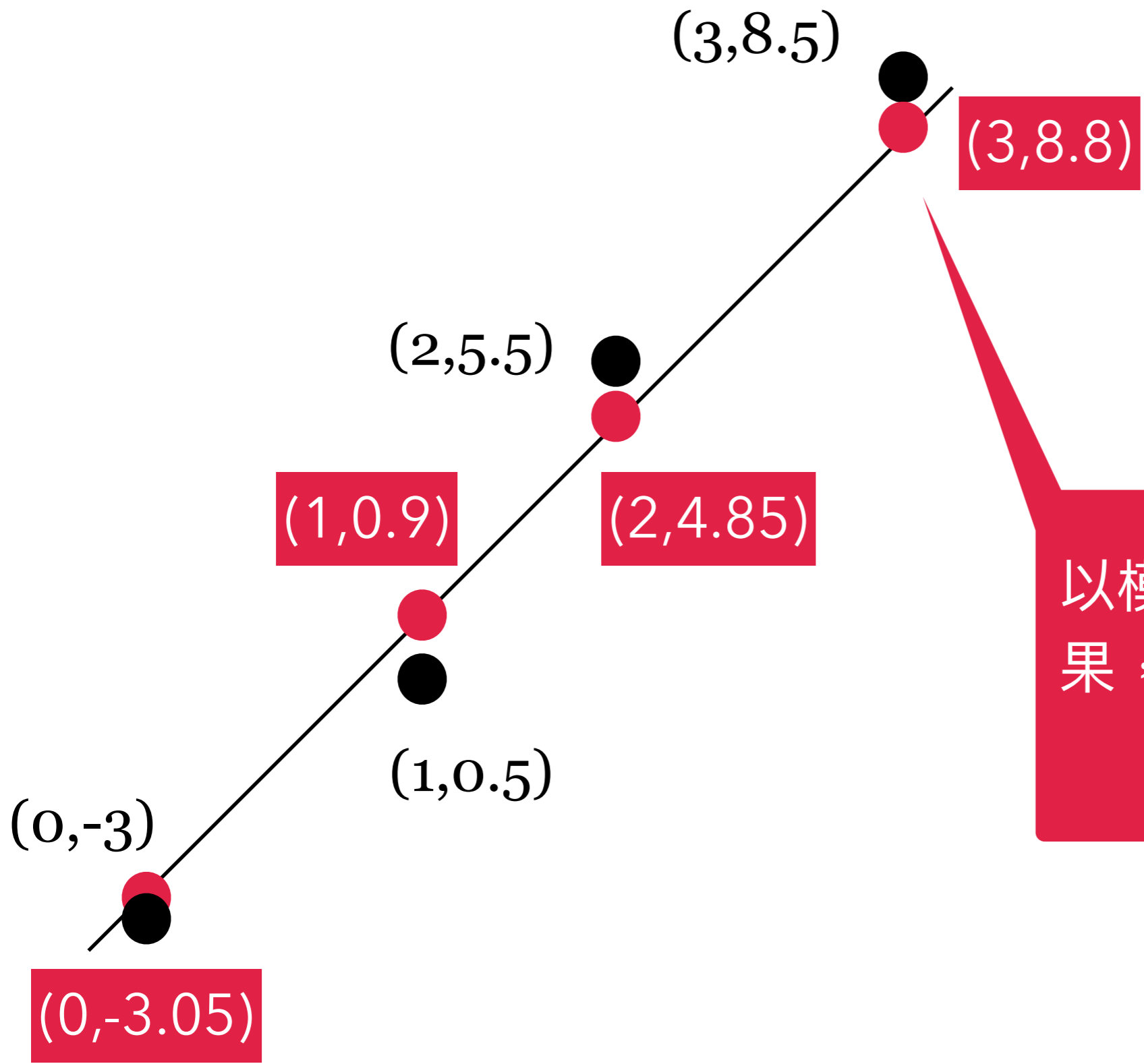
```
A = np.matrix([[2, 1], [1, 1], [3, 1], [0, 1]])  
b = np.matrix([[5.5], [0.5], [8.5], [-3]])
```

步驟三：求轉置矩陣

```
AT = np.matrix. (A)
```

步驟四：求最佳參數

```
B = A  
invB = (B)  
ans =
```



以模型校正或近似的結果，讓我們對實驗資料有進一步的認識

```
import numpy as np  
from numpy.linalg import inv
```

Matrix

```
A = np.matrix([range(1,5)])
```

```
matrix([[1, 2, 3, 4]])
```

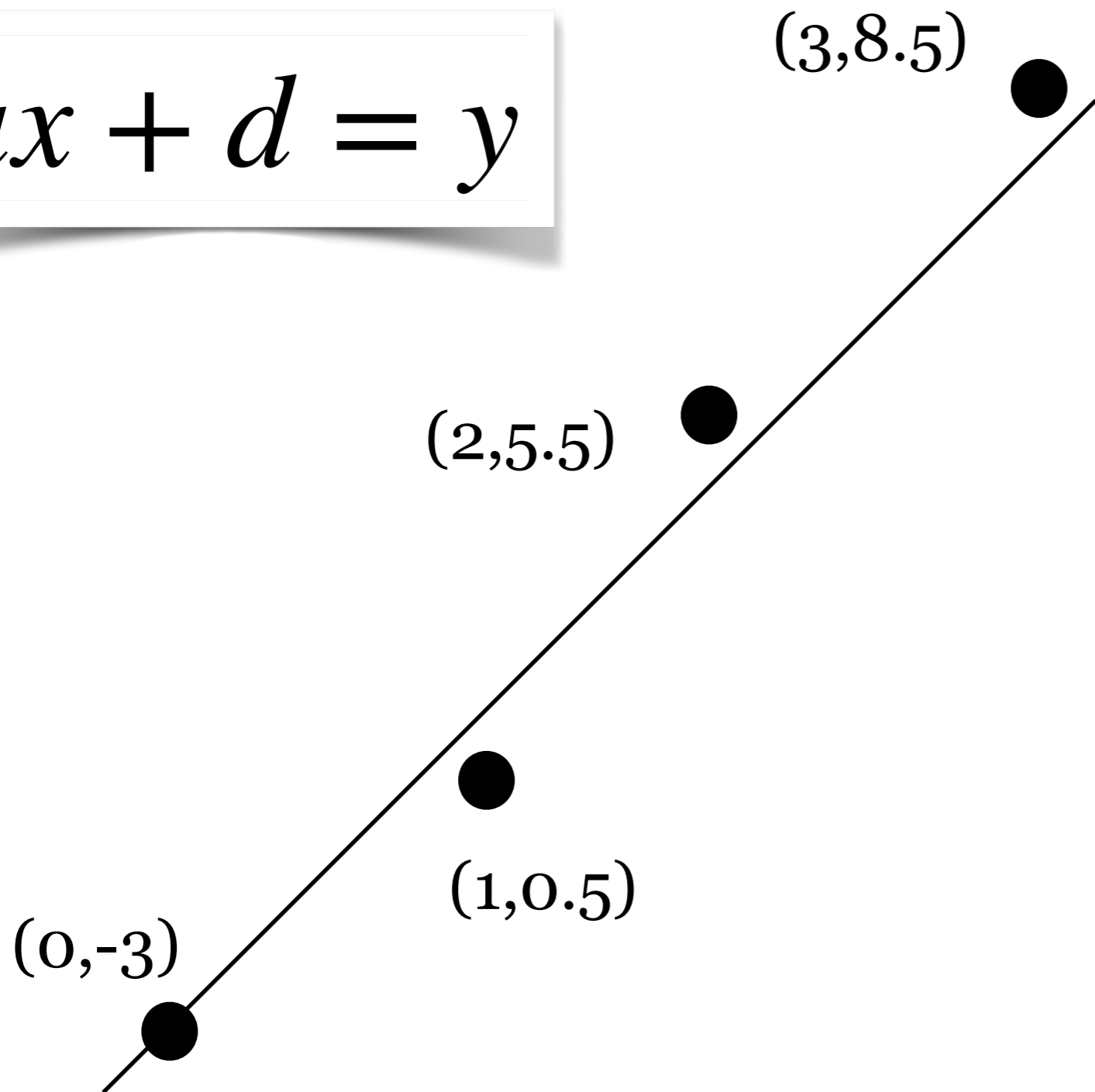
轉置矩陣

Matrix 轉置

```
A = np.matrix([range(1,5)])  
np.matrix.transpose(A)
```

```
>>> np.matrix.transpose(A)  
matrix([[1],  
        [2],  
        [3],  
        [4]])
```


$$ax + d = y$$



$$\begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = y$$

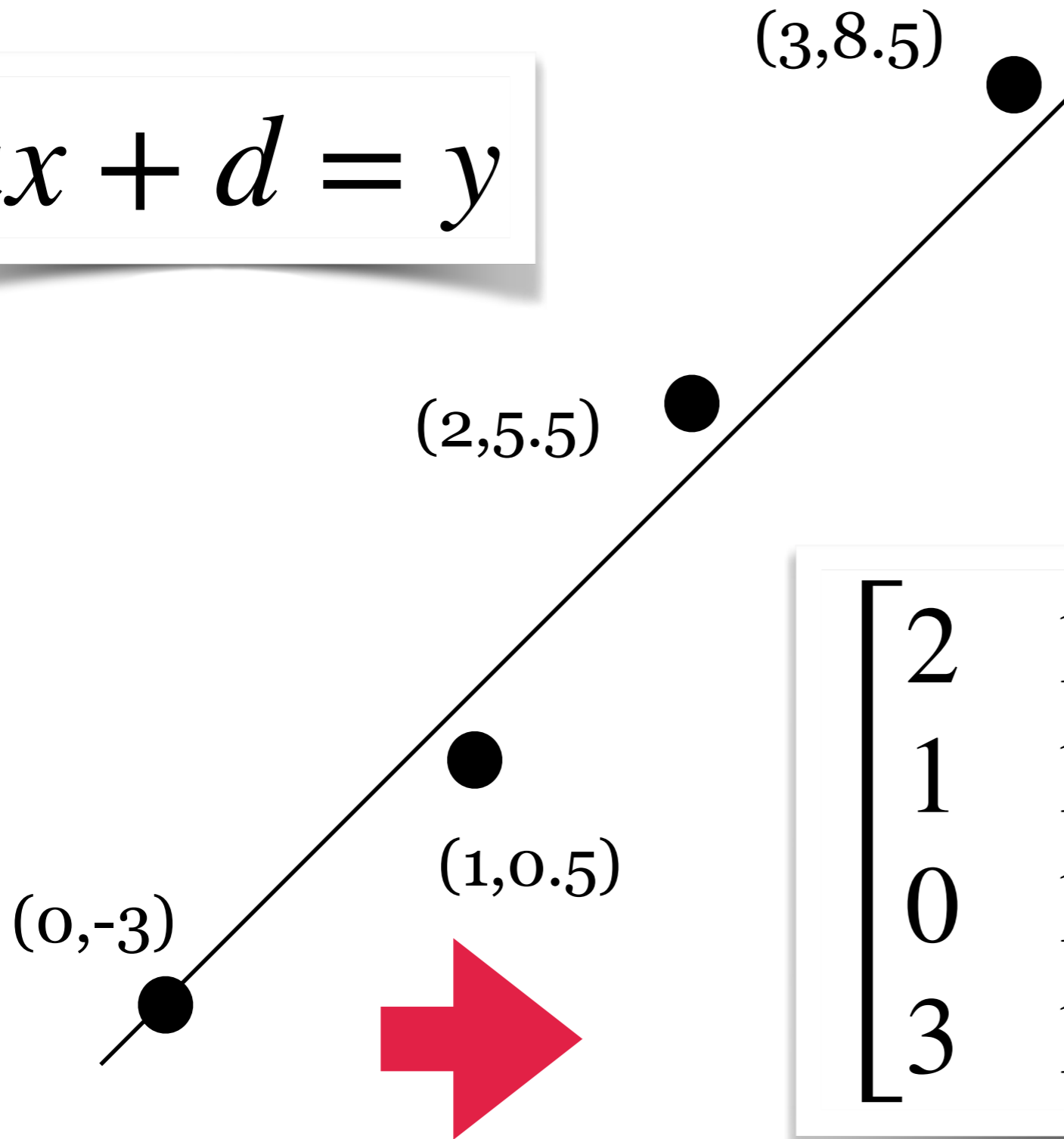
$$\begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = 5.5$$

$$\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = 0.5$$

$$\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = -3$$

$$\begin{bmatrix} 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = 8.5$$

$$ax + d = y$$



$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 0 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

長方形的系統

$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 0 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

矩陣A

$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 0 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

向量b

```
A = np.matrix([[2,1],[1,1],[3,1],[0,1]])  
b = np.matrix([[5.5],[0.5],[8.5],[-3]])
```

```
>>> A  
matrix([[2, 1],  
        [1, 1],  
        [3, 1],  
        [0, 1]])
```

```
>>> b  
matrix([[ 5.5],  
        [ 0.5],  
        [ 8.5],  
        [-3. ]])
```

```
A = np.matrix([[2, 1], [1, 1], [3, 1], [0, 1]])  
b = np.matrix([[5.5], [0.5], [8.5], [-3]])
```

可以求A的反矩陣嗎？

反矩陣一定是正方形的矩陣才有反矩陣

使用轉置矩陣
讓等號左邊變成
正方形矩陣

A^t A A^t b

$$\begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 0 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

```
A = np.matrix([[2, 1], [1, 1], [3, 1], [0, 1]])  
b = np.matrix([[5.5], [0.5], [8.5], [-3]])  
AT = np.matrix.transpose(A)  
AT @ A
```

```
>>> print(AT@A)  
[[14  6]  
 [ 6  4]]
```

```
>>> AT @ b  
matrix([[37. ],  
        [11.5]])
```


$$\begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 0 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

```
>>> print(AT@A)
[[14  6]
 [ 6  4]]
```

```
>>> AT @ b
matrix([[37. ],
        [11.5]])
```

$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

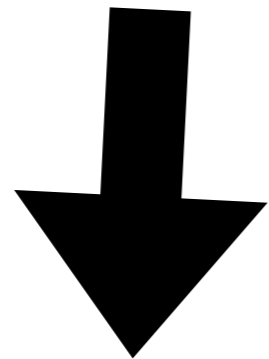
$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

可以使用反矩陣嗎？

等號左邊已經是正方形矩陣
那就可能有反矩陣

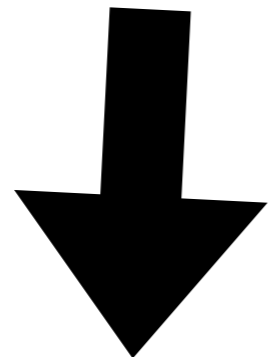
觀察：向量元素不同

討論： d 不是只代表截距
那代表時麼呢？



$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

d 代表截距+雜訊
因為點不在直線上



$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

$$ax + d = y$$

在上方，是正
雜訊

在下方，是負
雜訊

近似的概念：
忽略雜訊
直接求解

$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

最小（平方）近似誤差 提供近似概念

可以求最小（平方）近似誤差的直線

近似的概念：

忽略雜訊，直接求解

$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

$$\begin{bmatrix} a \\ d \end{bmatrix} = \mathit{inv}\left(\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \right) \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$


```
B = np.matrix([[14,6],[6,4]])  
invB = inv(B)  
ans = invB @ np.matrix([[37],[11.5]])
```

```
>>> A  
matrix([[14, 6],  
        [ 6, 4]])
```

```
>>> invA  
matrix([[ 0.2, -0.3],  
        [-0.3,  0.7]])
```

$$\text{inv}\left(\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix}\right) \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$

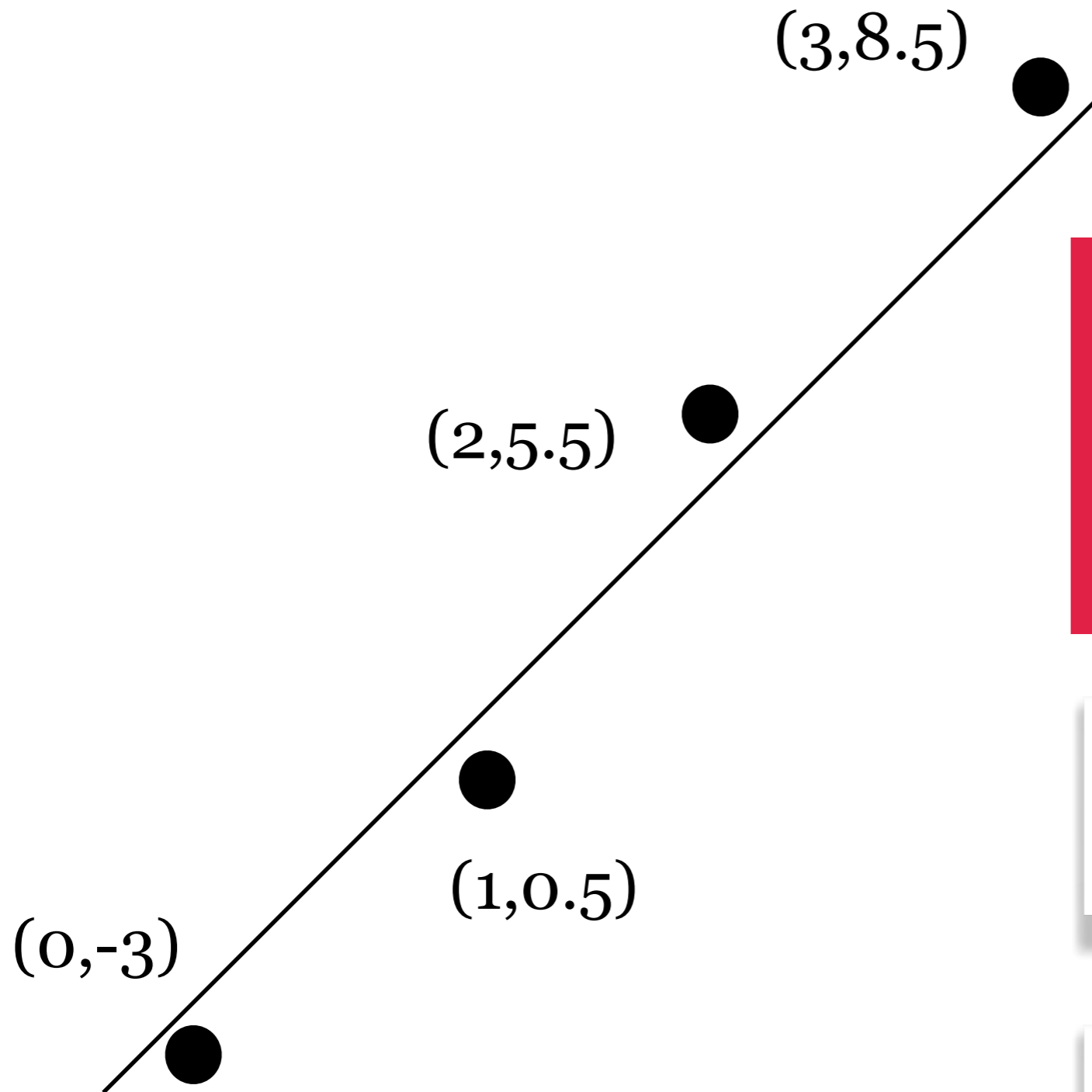
```
>>> ans  
matrix([[ 3.95],  
        [-3.05]])
```

$$ax + d = y$$

$$a = 3.95, \quad d = -3.05$$

```
>>> ans  
matrix([[ 3.95],  
        [-3.05]])
```

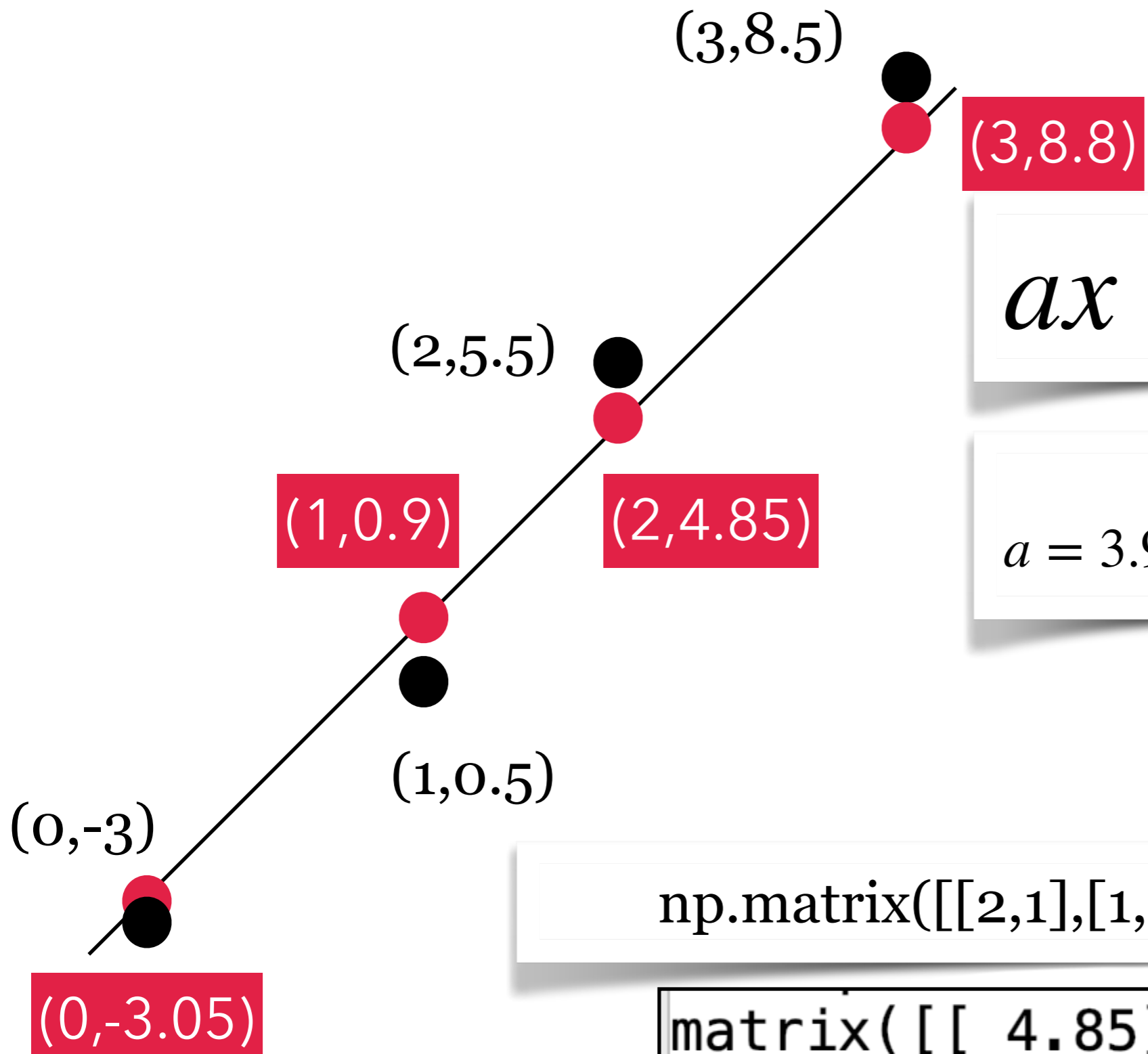
$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 37 \\ 11.5 \end{bmatrix}$$



四點不共線
如何求出最好的一條線，
描述這四點呢？

$$ax + d = y$$

$$a = 3.95, \quad d = -3.05$$

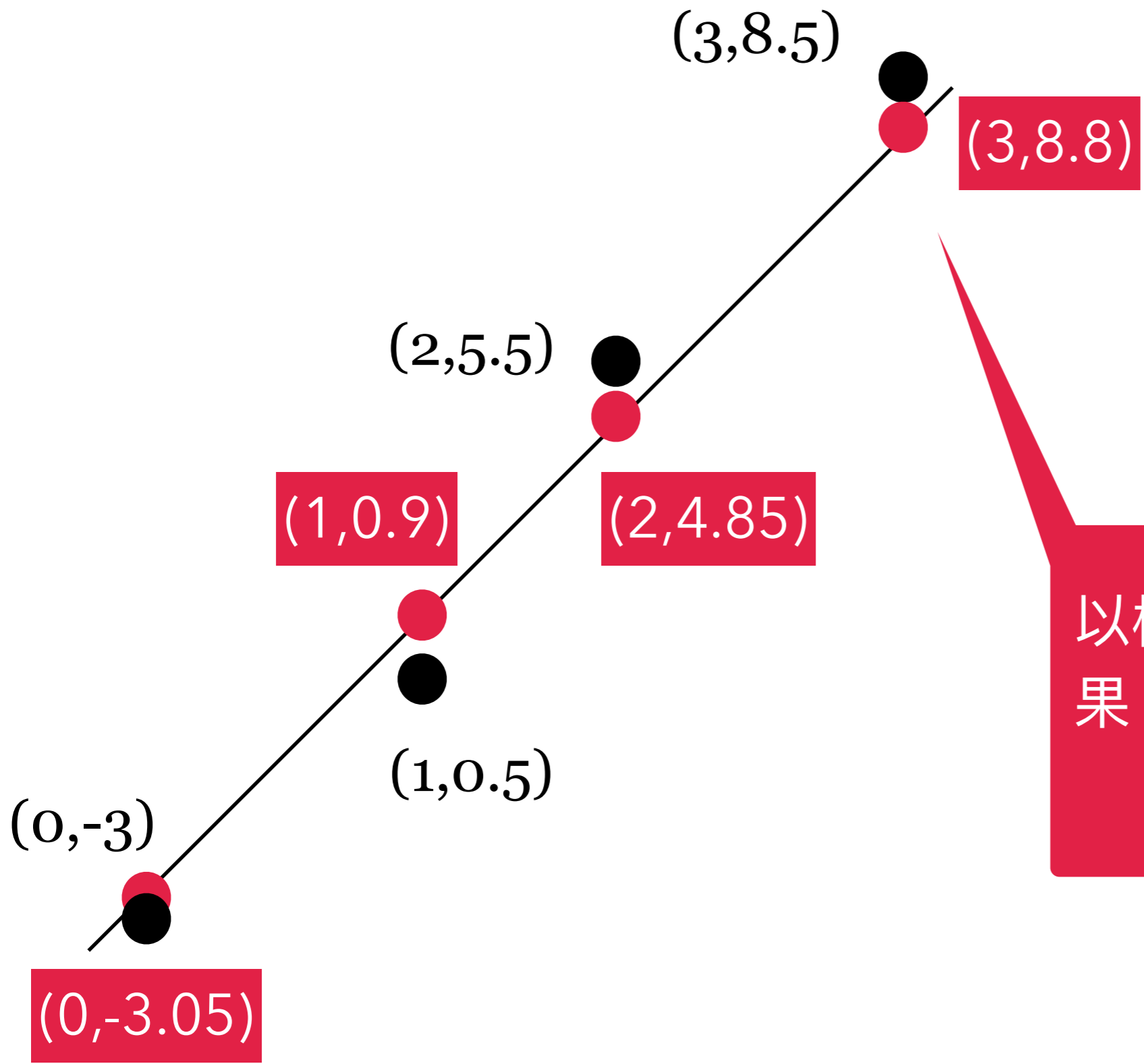


$$ax + d = y$$

$$a = 3.95, \quad d = -3.05$$

```
np.matrix([[2,1],[1,1],[3,1],[0,1]]) @ ans
```

```
matrix([[ 4.85],  
        [ 0.9 ],  
        [ 8.8 ],  
        [-3.05]])
```



以模型校正或近似的結果，讓我們對實驗資料有進一步的認識

方法

A^t A A^t b

$$\begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 0 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

$$B = A^t A$$

$$A^t$$

$$b$$

$$\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

B^{-1} A^t b

$$\begin{bmatrix} a \\ d \end{bmatrix} = \text{inv} \left(\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \right) \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

B^{-1} A^t b

$$\begin{bmatrix} a \\ d \end{bmatrix} = \text{inv}\left(\begin{bmatrix} 14 & 6 \\ 6 & 4 \end{bmatrix} \right) \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 5.5 \\ 0.5 \\ -3 \\ 8.5 \end{bmatrix}$$

$B = AT @ A$

$\text{inv}B = \text{inv}(B)$

$\text{ans} = \text{inv}B @ AT @ b$

步驟一：匯入
套裝

```
import numpy as np
from numpy.linalg import inv
```

步驟二：將資料以
矩陣A向量b表示

```
A = np.matrix([[2, 1], [1, 1], [3, 1], [0, 1]])
b = np.matrix([[5.5], [0.5], [8.5], [-3]])
```

步驟三：求轉置矩陣

```
AT = np.matrix.transpose(A)
```

步驟四：求最佳參數

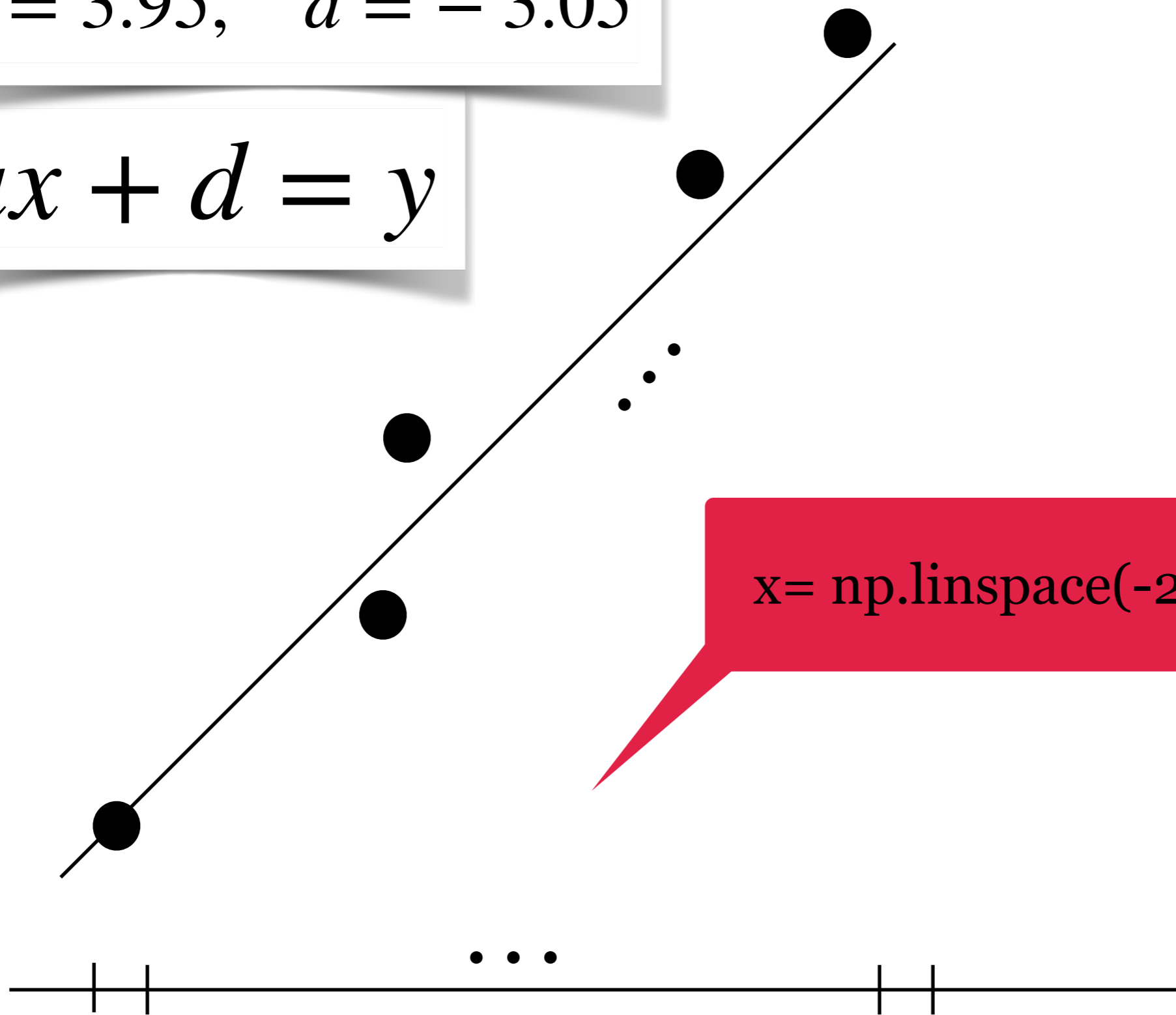
```
B = AT @ A
invB = inv(B)
ans = invB @ AT @ b
```

製作模擬的實驗資料

可以擴充到更多點？
在 $[-2\pi, 2\pi]$ 的區間取50點
對應到直線上，取值加雜訊

$$a = 3.95, \quad d = -3.05$$

$$ax + d = y$$

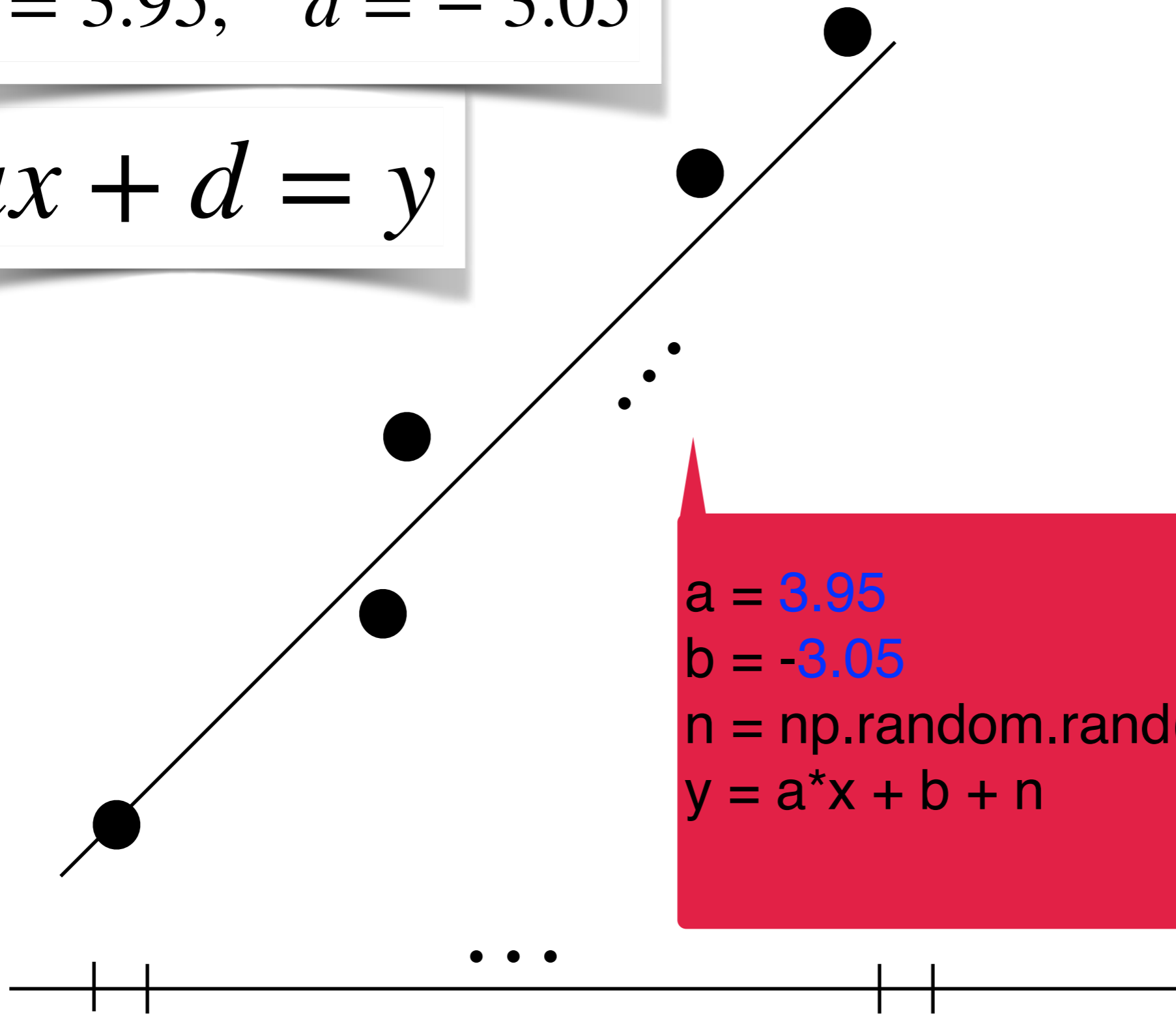


```
x = np.linspace(-2*np.pi, 2*np.pi)
```

$[-2\pi, 2\pi]$

$$a = 3.95, \quad d = -3.05$$

$$ax + d = y$$



```
a = 3.95  
b = -3.05  
n = np.random.rand(1, 50)  
y = a*x + b + n
```

$$[-2\pi, 2\pi]$$

```
x= np.linspace(-2*np.pi,2*np.pi)
```

```
a = 3.95
```

```
b = -3.05
```

```
n = np.random.rand(1,50)-0.5
```

```
x = np.linspace(-2*np.pi,2*np.pi)
```

```
y = a*x + b + 0.1 * n
```

```
vx = np.matrix(x)
vy = np.matrix(y)
```

```
A = np.hstack((np.transpose(vx), np.ones((50, 1))))
b = np.transpose(vy)
```


如何使用步驟三、步驟四
求直線參數？